

■ Matrizen

In[1]:= **A = Array[a, {4, 6}]**

$$\text{Out[1]} = \begin{pmatrix} a(1, 1) & a(1, 2) & a(1, 3) & a(1, 4) & a(1, 5) & a(1, 6) \\ a(2, 1) & a(2, 2) & a(2, 3) & a(2, 4) & a(2, 5) & a(2, 6) \\ a(3, 1) & a(3, 2) & a(3, 3) & a(3, 4) & a(3, 5) & a(3, 6) \\ a(4, 1) & a(4, 2) & a(4, 3) & a(4, 4) & a(4, 5) & a(4, 6) \end{pmatrix}$$

In[2]:= **Transpose[A]**

$$\text{Out[2]} = \begin{pmatrix} a(1, 1) & a(2, 1) & a(3, 1) & a(4, 1) \\ a(1, 2) & a(2, 2) & a(3, 2) & a(4, 2) \\ a(1, 3) & a(2, 3) & a(3, 3) & a(4, 3) \\ a(1, 4) & a(2, 4) & a(3, 4) & a(4, 4) \\ a(1, 5) & a(2, 5) & a(3, 5) & a(4, 5) \\ a(1, 6) & a(2, 6) & a(3, 6) & a(4, 6) \end{pmatrix}$$

In[3]:= **3 A**

$$\text{Out[3]} = \begin{pmatrix} 3 a(1, 1) & 3 a(1, 2) & 3 a(1, 3) & 3 a(1, 4) & 3 a(1, 5) & 3 a(1, 6) \\ 3 a(2, 1) & 3 a(2, 2) & 3 a(2, 3) & 3 a(2, 4) & 3 a(2, 5) & 3 a(2, 6) \\ 3 a(3, 1) & 3 a(3, 2) & 3 a(3, 3) & 3 a(3, 4) & 3 a(3, 5) & 3 a(3, 6) \\ 3 a(4, 1) & 3 a(4, 2) & 3 a(4, 3) & 3 a(4, 4) & 3 a(4, 5) & 3 a(4, 6) \end{pmatrix}$$

In[4]:= **X = {{x₁}, {x₂}, {x₃}, {x₄}, {x₅}, {x₆}}**

$$\text{Out[4]} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{pmatrix}$$

In[5]:= **A.X**

$$\text{Out[5]} = \begin{pmatrix} a(1, 1)x_1 + a(1, 2)x_2 + a(1, 3)x_3 + a(1, 4)x_4 + a(1, 5)x_5 + a(1, 6)x_6 \\ a(2, 1)x_1 + a(2, 2)x_2 + a(2, 3)x_3 + a(2, 4)x_4 + a(2, 5)x_5 + a(2, 6)x_6 \\ a(3, 1)x_1 + a(3, 2)x_2 + a(3, 3)x_3 + a(3, 4)x_4 + a(3, 5)x_5 + a(3, 6)x_6 \\ a(4, 1)x_1 + a(4, 2)x_2 + a(4, 3)x_3 + a(4, 4)x_4 + a(4, 5)x_5 + a(4, 6)x_6 \end{pmatrix}$$

In[6]:= **B = Array[b, {4, 6}]**

$$\text{Out[6]} = \begin{pmatrix} b(1, 1) & b(1, 2) & b(1, 3) & b(1, 4) & b(1, 5) & b(1, 6) \\ b(2, 1) & b(2, 2) & b(2, 3) & b(2, 4) & b(2, 5) & b(2, 6) \\ b(3, 1) & b(3, 2) & b(3, 3) & b(3, 4) & b(3, 5) & b(3, 6) \\ b(4, 1) & b(4, 2) & b(4, 3) & b(4, 4) & b(4, 5) & b(4, 6) \end{pmatrix}$$

In[7]:= **A + B**

$$\text{Out[7]} = \begin{pmatrix} a(1, 1) + b(1, 1) & a(1, 2) + b(1, 2) & a(1, 3) + b(1, 3) & a(1, 4) + b(1, 4) & a(1, 5) + b(1, 5) & a(1, 6) + b(1, 6) \\ a(2, 1) + b(2, 1) & a(2, 2) + b(2, 2) & a(2, 3) + b(2, 3) & a(2, 4) + b(2, 4) & a(2, 5) + b(2, 5) & a(2, 6) + b(2, 6) \\ a(3, 1) + b(3, 1) & a(3, 2) + b(3, 2) & a(3, 3) + b(3, 3) & a(3, 4) + b(3, 4) & a(3, 5) + b(3, 5) & a(3, 6) + b(3, 6) \\ a(4, 1) + b(4, 1) & a(4, 2) + b(4, 2) & a(4, 3) + b(4, 3) & a(4, 4) + b(4, 4) & a(4, 5) + b(4, 5) & a(4, 6) + b(4, 6) \end{pmatrix}$$

In[8]:= **A.B**

$$\text{Dot::dotsh : Tensors } \begin{pmatrix} a(1,1) & a(1,2) & a(1,3) & a(1,4) & a(1,5) & a(1,6) \\ a(2,1) & a(2,2) & a(2,3) & a(2,4) & a(2,5) & a(2,6) \\ a(3,1) & a(3,2) & a(3,3) & a(3,4) & a(3,5) & a(3,6) \\ a(4,1) & a(4,2) & a(4,3) & a(4,4) & a(4,5) & a(4,6) \end{pmatrix} \text{ and } \begin{pmatrix} b(1,1) & b(1,2) & b(1,3) & b(1,4) & b(1,5) & b(1,6) \\ b(2,1) & b(2,2) & b(2,3) & b(2,4) & b(2,5) & b(2,6) \\ b(3,1) & b(3,2) & b(3,3) & b(3,4) & b(3,5) & b(3,6) \\ b(4,1) & b(4,2) & b(4,3) & b(4,4) & b(4,5) & b(4,6) \end{pmatrix} \text{ have incompatible shapes. } \gg$$

$$\text{Out[8]} = \begin{pmatrix} a(1,1) & a(1,2) & a(1,3) & a(1,4) & a(1,5) & a(1,6) \\ a(2,1) & a(2,2) & a(2,3) & a(2,4) & a(2,5) & a(2,6) \\ a(3,1) & a(3,2) & a(3,3) & a(3,4) & a(3,5) & a(3,6) \\ a(4,1) & a(4,2) & a(4,3) & a(4,4) & a(4,5) & a(4,6) \end{pmatrix} \cdot \begin{pmatrix} b(1,1) & b(1,2) & b(1,3) & b(1,4) & b(1,5) & b(1,6) \\ b(2,1) & b(2,2) & b(2,3) & b(2,4) & b(2,5) & b(2,6) \\ b(3,1) & b(3,2) & b(3,3) & b(3,4) & b(3,5) & b(3,6) \\ b(4,1) & b(4,2) & b(4,3) & b(4,4) & b(4,5) & b(4,6) \end{pmatrix}$$

In[9]:= **Transpose[A].B**

$$\text{Out[9]} = \begin{pmatrix} a(1,1)b(1,1) + a(2,1)b(2,1) + a(3,1)b(3,1) + a(4,1)b(4,1) & a(1,1)b(1,2) + a(2,1)b(2,2) + a(3,1)b(3,2) + a(4,1)b(4,2) \\ a(1,2)b(1,1) + a(2,2)b(2,1) + a(3,2)b(3,1) + a(4,2)b(4,1) & a(1,2)b(1,2) + a(2,2)b(2,2) + a(3,2)b(3,2) + a(4,2)b(4,2) \\ a(1,3)b(1,1) + a(2,3)b(2,1) + a(3,3)b(3,1) + a(4,3)b(4,1) & a(1,3)b(1,2) + a(2,3)b(2,2) + a(3,3)b(3,2) + a(4,3)b(4,2) \\ a(1,4)b(1,1) + a(2,4)b(2,1) + a(3,4)b(3,1) + a(4,4)b(4,1) & a(1,4)b(1,2) + a(2,4)b(2,2) + a(3,4)b(3,2) + a(4,4)b(4,2) \\ a(1,5)b(1,1) + a(2,5)b(2,1) + a(3,5)b(3,1) + a(4,5)b(4,1) & a(1,5)b(1,2) + a(2,5)b(2,2) + a(3,5)b(3,2) + a(4,5)b(4,2) \\ a(1,6)b(1,1) + a(2,6)b(2,1) + a(3,6)b(3,1) + a(4,6)b(4,1) & a(1,6)b(1,2) + a(2,6)b(2,2) + a(3,6)b(3,2) + a(4,6)b(4,2) \end{pmatrix}$$

In[10]:= **A = {{2, 1}, {-3, -2}}**

$$\text{Out[10]} = \begin{pmatrix} 2 & 1 \\ -3 & -2 \end{pmatrix}$$

In[11]:= **B = {{-1, 2, 1}, {-5, 0, 3/2}}**

$$\text{Out[11]} = \begin{pmatrix} -1 & 2 & 1 \\ -5 & 0 & \frac{3}{2} \end{pmatrix}$$

In[12]:= **A.B**

$$\text{Out[12]} = \begin{pmatrix} -7 & 4 & \frac{7}{2} \\ 13 & -6 & -6 \end{pmatrix}$$

In[13]:= **B.A**

$$\text{Dot::dotsh : Tensors } \begin{pmatrix} -1 & 2 & 1 \\ -5 & 0 & \frac{3}{2} \end{pmatrix} \text{ and } \begin{pmatrix} 2 & 1 \\ -3 & -2 \end{pmatrix} \text{ have incompatible shapes. } \gg$$

$$\text{Out[13]} = \begin{pmatrix} -1 & 2 & 1 \\ -5 & 0 & \frac{3}{2} \end{pmatrix} \cdot \begin{pmatrix} 2 & 1 \\ -3 & -2 \end{pmatrix}$$

In[14]:= **A = {{1, 1, 1 + i, 0}, {-1, 2, 0, 0}}, {1, 0, 3, -i}}**

$$\text{Out[14]} = \begin{pmatrix} 1 & 1 & 1 + i & 0 \\ -1 & 2 & 0 & 0 \\ 1 & 0 & 3 & -i \end{pmatrix}$$

In[15]:= **B** = {{5, 9, 2}, {0, 0, 1}, {1, -1, -2}, {-2, 3, 4}}

$$\text{Out[15]} = \begin{pmatrix} 5 & 9 & 2 \\ 0 & 0 & 1 \\ 1 & -1 & -2 \\ -2 & 3 & 4 \end{pmatrix}$$

In[16]:= **A.B**

$$\text{Out[16]} = \begin{pmatrix} 6+i & 8-i & 1-2i \\ -5 & -9 & 0 \\ 8+2i & 6-3i & -4-4i \end{pmatrix}$$

In[17]:= **A** = {{2, -1, -3}}

$$\text{Out[17]} = \begin{pmatrix} 2 & -1 & -3 \end{pmatrix}$$

In[18]:= **B** = {{1}, {i}, {-1}}

$$\text{Out[18]} = \begin{pmatrix} 1 \\ i \\ -1 \end{pmatrix}$$

In[19]:= **A.B**

$$\text{Out[19]} = \begin{pmatrix} 5-i \end{pmatrix}$$

In[20]:= **B.A**

$$\text{Out[20]} = \begin{pmatrix} 2 & -1 & -3 \\ 2i & -i & -3i \\ -2 & 1 & 3 \end{pmatrix}$$

In[21]:= **A** = {{a, 1}, {3, 0}}

$$\text{Out[21]} = \begin{pmatrix} a & 1 \\ 3 & 0 \end{pmatrix}$$

■ Inverse Matrizen

In[22]:= **Inverse[A]**

$$\text{Out[22]} = \begin{pmatrix} 0 & \frac{1}{3} \\ 1 & -\frac{a}{3} \end{pmatrix}$$

In[23]:= **Inverse[A].A**

$$\text{Out[23]} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

In[24]:= **A.Inverse[A]**

$$\text{Out[24]} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

In[25]:= **X** = {{x₁}, {x₂}}

$$\text{Out[25]} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

In[26]:= **B = {{b₁}, {b₂}}**

$$\text{Out[26]} = \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$$

In[27]:= **Solve[A.X == B, {x₁, x₂}]**

$$\text{Out[27]} = \left\{ \left\{ x_1 \rightarrow \frac{b_2}{3}, x_2 \rightarrow \frac{1}{3} (3 b_1 - a b_2) \right\} \right\}$$

In[28]:= **Inverse[A].B**

$$\text{Out[28]} = \begin{pmatrix} \frac{b_2}{3} \\ b_1 - \frac{a b_2}{3} \end{pmatrix}$$

In[29]:= **A = {{i, 0, 1}, {1, 0, i}, {0, 1, 0}}**

$$\text{Out[29]} = \begin{pmatrix} i & 0 & 1 \\ 1 & 0 & i \\ 0 & 1 & 0 \end{pmatrix}$$

In[30]:= **Inverse[A]**

$$\text{Out[30]} = \begin{pmatrix} -\frac{i}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 1 \\ \frac{1}{2} & -\frac{i}{2} & 0 \end{pmatrix}$$

In[31]:= **Aerw = Transpose[Join[Transpose[A], IdentityMatrix[3]]]**

$$\text{Out[31]} = \begin{pmatrix} i & 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & i & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 \end{pmatrix}$$

In[32]:= **RowReduce[Aerw]**

$$\text{Out[32]} = \begin{pmatrix} 1 & 0 & 0 & -\frac{i}{2} & \frac{1}{2} & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & \frac{1}{2} & -\frac{i}{2} & 0 \end{pmatrix}$$

In[33]:= **A = {{Cos[φ], -Sin[φ]}, {Sin[φ], Cos[φ]}}**

$$\text{Out[33]} = \begin{pmatrix} \cos(\phi) & -\sin(\phi) \\ \sin(\phi) & \cos(\phi) \end{pmatrix}$$

In[34]:= **Inverse[A]**

$$\text{Out[34]} = \begin{pmatrix} \frac{\cos(\phi)}{\cos^2(\phi)+\sin^2(\phi)} & \frac{\sin(\phi)}{\cos^2(\phi)+\sin^2(\phi)} \\ -\frac{\sin(\phi)}{\cos^2(\phi)+\sin^2(\phi)} & \frac{\cos(\phi)}{\cos^2(\phi)+\sin^2(\phi)} \end{pmatrix}$$

In[35]:= **Inverse[A] // Simplify**

$$\text{Out[35]} = \begin{pmatrix} \cos(\phi) & \sin(\phi) \\ -\sin(\phi) & \cos(\phi) \end{pmatrix}$$

In[36]:= **Aerw = Transpose[Join[Transpose[A], IdentityMatrix[2]]]**

$$\text{Out[36]} = \begin{pmatrix} \cos(\phi) & -\sin(\phi) & 1 & 0 \\ \sin(\phi) & \cos(\phi) & 0 & 1 \end{pmatrix}$$

In[37]:= **RowReduce[Aerw]**

$$\text{Out[37]} = \begin{pmatrix} 1 & 0 & \frac{\cos(\phi)}{\cos^2(\phi)+\sin^2(\phi)} & \frac{\sin(\phi)}{\cos^2(\phi)+\sin^2(\phi)} \\ 0 & 1 & -\frac{\sin(\phi)}{\cos^2(\phi)+\sin^2(\phi)} & \frac{\cos(\phi)}{\cos^2(\phi)+\sin^2(\phi)} \end{pmatrix}$$

In[38]:= **RowReduce[Aerw] // Simplify**

$$\text{Out[38]} = \begin{pmatrix} 1 & 0 & \cos(\phi) & \sin(\phi) \\ 0 & 1 & -\sin(\phi) & \cos(\phi) \end{pmatrix}$$

In[39]:= **A = {{a, 1}, {3, 0}}**

$$\text{Out[39]} = \begin{pmatrix} a & 1 \\ 3 & 0 \end{pmatrix}$$

In[40]:= **Inverse[A]**

$$\text{Out[40]} = \begin{pmatrix} 0 & \frac{1}{3} \\ 1 & -\frac{a}{3} \end{pmatrix}$$

■ Lösen von Gleichungssystemen mit Matrizen

In[41]:= **A = {{0, 2, 1}, {1/2, 3, 0}, {5, 0, 2}}**

$$\text{Out[41]} = \begin{pmatrix} 0 & 2 & 1 \\ \frac{1}{2} & 3 & 0 \\ 5 & 0 & 2 \end{pmatrix}$$

In[42]:= **b = {{2}, {2}, {1}}**

$$\text{Out[42]} = \begin{pmatrix} 2 \\ 2 \\ 1 \end{pmatrix}$$

In[43]:= **Aerw = Transpose[Join[Transpose[A], Transpose[b]]]**

$$\text{Out[43]} = \begin{pmatrix} 0 & 2 & 1 & 2 \\ \frac{1}{2} & 3 & 0 & 2 \\ 5 & 0 & 2 & 1 \end{pmatrix}$$

In[44]:= **RowReduce[Aerw]**

$$\text{Out[44]} = \begin{pmatrix} 1 & 0 & 0 & -\frac{1}{17} \\ 0 & 1 & 0 & \frac{23}{34} \\ 0 & 0 & 1 & \frac{11}{17} \end{pmatrix}$$

In[45]:= **Inverse[A].b**

$$\text{Out[45]} = \begin{pmatrix} -\frac{1}{17} \\ \frac{23}{34} \\ \frac{11}{17} \end{pmatrix}$$

In[46]:= **A = { {2, 3, 3}, {1, 5, $\frac{5}{2}$ }, {7, 21, $\frac{27}{2}$ } }**

$$\text{Out[46]} = \begin{pmatrix} 2 & 3 & 3 \\ 1 & 5 & \frac{5}{2} \\ 7 & 21 & \frac{27}{2} \end{pmatrix}$$

In[47]:= **b = { {-5}, {0}, {-10} }**

$$\text{Out[47]} = \begin{pmatrix} -5 \\ 0 \\ -10 \end{pmatrix}$$

In[48]:= **Aerw = Transpose[Join[Transpose[A], Transpose[b]]]**

$$\text{Out[48]} = \begin{pmatrix} 2 & 3 & 3 & -5 \\ 1 & 5 & \frac{5}{2} & 0 \\ 7 & 21 & \frac{27}{2} & -10 \end{pmatrix}$$

In[49]:= **RowReduce[Aerw]**

$$\text{Out[49]} = \begin{pmatrix} 1 & 0 & \frac{15}{14} & -\frac{25}{7} \\ 0 & 1 & \frac{2}{7} & \frac{5}{7} \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

In[50]:= **Inverse[A].b**

Inverse::sing : Matrix $\begin{pmatrix} 2 & 3 & 3 \\ 1 & 5 & \frac{5}{2} \\ 7 & 21 & \frac{27}{2} \end{pmatrix}$ is singular. >>

$$\text{Out[50]} = \begin{pmatrix} 2 & 3 & 3 \\ 1 & 5 & \frac{5}{2} \\ 7 & 21 & \frac{27}{2} \end{pmatrix}^{-1} \cdot \begin{pmatrix} -5 \\ 0 \\ -10 \end{pmatrix}$$

In[51]:= **A = { { $\frac{2}{3}$, 4, $-\frac{3}{2}$ }, { $\frac{1}{2}$, -2, 3}, { $\frac{7}{6}$, $\frac{26}{3}$, -4} }**

$$\text{Out[51]} = \begin{pmatrix} \frac{2}{3} & 4 & -\frac{3}{2} \\ \frac{1}{2} & -2 & 3 \\ \frac{7}{6} & \frac{26}{3} & -4 \end{pmatrix}$$

In[52]:= **b = { {5}, {-3}, {-1} }**

$$\text{Out[52]} = \begin{pmatrix} 5 \\ -3 \\ -1 \end{pmatrix}$$

In[53]:= **Aerw = Transpose[Join[Transpose[A], Transpose[b]]]**

$$\text{Out[53]} = \begin{pmatrix} \frac{2}{3} & 4 & -\frac{3}{2} & 5 \\ \frac{1}{2} & -2 & 3 & -3 \\ \frac{7}{6} & \frac{26}{3} & -4 & -1 \end{pmatrix}$$

In[54]:= **RowReduce[Aerw]**

$$\text{Out[54]} = \begin{pmatrix} 1 & 0 & \frac{27}{10} & 0 \\ 0 & 1 & -\frac{33}{40} & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

In[55]:= **Inverse[A].b**

Inverse::sing : Matrix $\begin{pmatrix} \frac{2}{3} & 4 & -\frac{3}{2} \\ \frac{1}{2} & -2 & 3 \\ \frac{7}{6} & \frac{26}{3} & -4 \end{pmatrix}$ is singular. >>

$$\text{Out[55]} = \begin{pmatrix} \frac{2}{3} & 4 & -\frac{3}{2} \\ \frac{1}{2} & -2 & 3 \\ \frac{7}{6} & \frac{26}{3} & -4 \end{pmatrix}^{-1} \cdot \begin{pmatrix} 5 \\ -3 \\ -1 \end{pmatrix}$$